

The HDT Adroit system is designed for harsh environment. All our manipulator arms meet the demanding IP66 waterproof standard – including high-pressure wash down. Arms operate in below-freezing temperatures as well as in very hot

KEY FEATURES

- Customizable modular system of bases, joints, connectors and end-effectors
- High payload-to-mass ratio and excellent power efficiency

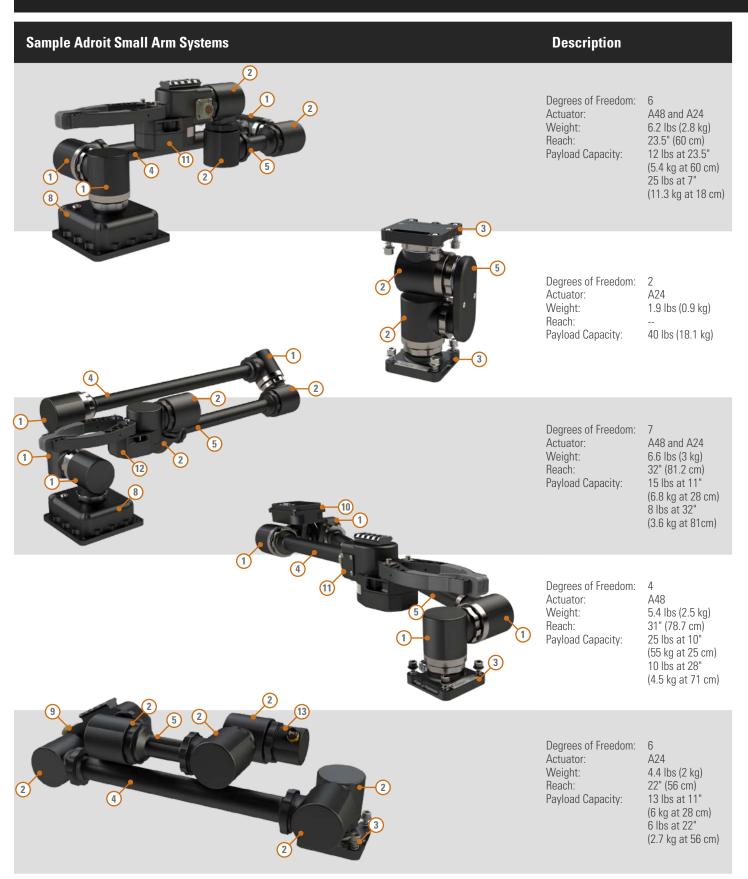
and humid conditions.

- Through-joint wiring, with slip-rings for continuous rotation
- Eight signal lines reserved for customer (up to gigabit Ethernet and/or analog video)
- Up to 100 W (24 V at 4 A) can be supplied to customer's accessories
- Accessory mounting points can be added anywhere on arm, with power and signal

- Input power 12 to 30 volts (speed and torque limited at less than 24 volts)
- Power consumption is less than 1 W per joint in standby, ~10 W per joint with no load moving at half speed, and ~50 W per joint during fast rotation or heavy lift
- Waterproof standard: IP66 (high-pressure wash down); optional: IP67 (1 m submersion in water)
- Operating temperature standard: -4° to 140° F (-20 to 60 C); optional: -40° to 160° F (-40 to 80 C)

ADROIT® SMALL ARM SYSTEMS

Robotic Arms Built from A24 and A48 Drives



XHDT.

Actuators see page 4 for drive performance details







48 Nm (35 ft-lb) - 40° / S Optional: Torque sensing Marinized available





24 NM (18 ft-lb) - 65° / S Optional: Torque sensing

End Effectors





A48 Pincer

48 lbf (210 N) Tip pinch 6" (15cm) Diameter grip (Marinized available)

Optional: Comms breakout Power breakout Torque Sensing







Pedestal

Male or Female



Male to Male

Standard lengths: 250, 300, 350, 400mm





Male to Female

Standard lengths: 140, 270, 400mm





Male to Female Parallel





Male to Female Right Angle

Computers





Pedestal Computer

Male or Female Marinized available





Arm Mounted Inline

Power and comms breakouts Picatinny accessory mount





Arm Mounted Offset

Power and comms breakouts Picatinny mount option Bench mount option





A24 Pincer

24 lbf (105 N) Tip pinch 5" (13cm) Diameter grip





Customer Payload Adapter

Male or Female connection Power and comms breakout M8 / M12 Industrial connector typical

Quick Release Pincer Fingers



Standard 5" (13cm)



Bypass



Flat Hook



Large Diameter 6" (15 cm)



Extended Tip







To remove finger...

Press joint button

Finger is released

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ACCESSORIES AND CUSTOMIZATION OPTIONS

Blade on Gripper Finger



Camera In-Line Module



Wrench for Assembly/Disassembly



Gripper-Actuated Wire Cutters



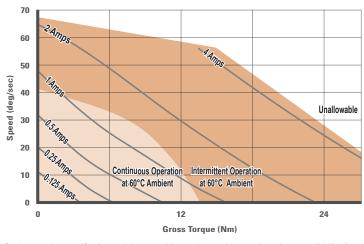
ACTUATOR SPECIFICATIONS

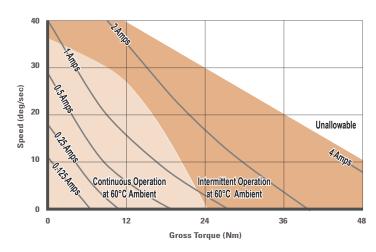


A24: Single Joint Bus Amperes at 24V
Active Driving (joints can hold torque at near zero power)



A48: Single Joint Bus Amperes at 24V
Active Driving (joints can hold torque at near zero power)





Products, product specifications and data are subject to change without notice to improve reliability, function, and/or design. Please contact Customer Service at 800.969.8527 for the most up-to-date product information.